KCT-2500

Speed Dome Camera Controller

Operation Manual

Please read this operation manual before using this device and use the device properly. Also, please keep this manual with care to ensure easy access at any time.

SAFETY PRECAUTIONS





The lighting flash with a arrowhead symbol, in an equilateral triangle, is intended to allert the user. There is uninsulated "dangerous voltage" presence near by the product's enclosure which may be risk of to persons.



The exclamation point within an equilateral triangle is intended to alert the user to reference of the important operating and maintenance (servicing) instructions.

THE PRODUCT CODE MARKED ON THE BOTTOM COVER PLEASE FILL THE CODE IN THE FOLLOWING BLANK PLEASE SAMING THIS SPECIFICATION CAREFULLY, SO THAT CHECKING MODEL:

PROJUCT CODE:

INDEX

| 1. Summary | 1 |
|---|--------|
| 2. Introduction of Functions | 1 |
| 3. Introduction of the Keyboard Panel | 1 |
| 3.1 The Sketch of the Front Panel and Description of Buttons3.2 Rear Panel | 1 3 |
| 4. Setting of the Keyboard | 3 |
| 4.1 Setup of the Protocol and the Default Baud Rate | 3 |
| 4.2 Setup of the Baud Rate of Communication | 3 |
| 5. Operation of the Keyboard | 4 |
| 6. Installation and Connection | •••••6 |
| 7. Technical Specifications | 8 |
| 8. Points for Attention | 8 |

I. Summary

The keyboard controller is used for terminal receivers such as the intelligent speed dome and the decoder etc. Taking the EIA/RS-485 electrical interface between the keyboard and the receiver, one keyboard can control as much as 32 speed dome and decoders without driving the bus and the maximum communication distance between the keyboard and the receiver is up to 1.2 km. It is very easy for operating and setting the speed dome camera. The controller is also to control the terminal receiver to achieve the function of controlling pan/tilt, lens and etc.

Main Functions:

- Set the address range of the dome camera and the decoder : $0 \sim 255$.
- To directly control full functions of speed dome camera. For example: turn ON/OFF camera BLC.
- To operate the pan/tilt of speed dome camera moving in different speed level
- To set up 128 preset positions and 6 cruising tracks for speed dome camera and call any of them. Each cruising track contains up to 16 preset positions. You can set up the staying period and moving speed for each preset position.
- To control speed dome camera by manual/auto operation. It is possible to change the initial set through setting the speed dome camera menu.
- Manually control the focus, zoom and iris of the camera.

II. Introduction of Functions

Select Camera (0~255)



Direct Control on Decoder Control front devices such as the decoder etc.

III. Introduction of the Keyboard Panel

1. The Sketch of the Front Panel and Description of Buttons (Figure 1)

There are speed joystick, buttons and LCD on the front panel of the control keyboard. The display is used to

show the status of the system as well as operation information. The joystick controls the upward, downward, leftward and rightward speed motion of the speed dome. The description of buttons is as follows:



(Figure 1)

- Func (1 cam): Set special function of the system together with other buttons.
- Zoom (Full screen): Show picture of the camera in full screen. Press Zoom again to review a 2 Zoom of the selected camera.
- **PIP (up arrow):** Show picture of the camera in PIP mode (Picture-in-Picture).
- 2×2 (down arrow): Show picture of the camera in 4-frame.
- **3×3 (left arrow):** Show picture of the camera in 9-frame.
- **4×4 (right arrow):** Show picture of the camera in 16-frame.
- Live : Show live picture of the camera at current mode.
- Tape : Playback pictures ; Function + Tape: Playback video information of VCR.
- CAM: in multiplexer mode: Used with camera buttons to select cameras to display in the full, PIP,

2×2,3×3,4×4 formats. in speed dome mode :Select address of the intelligent speed dome.

- **F2: in multiplexer mode:** Start automatic switching of cameras. This button is also used during setup to turn on all motion detection targets. **in speed dome mode :**Auxiliary control buttons.
- **CALL:** To call the preset position.
- **PRESET** : To set the preset position.
- **SHOT** : To set up or call cruising track.

- AUTO : To control auto-horizontal rotation for pan/tilt.
- **WIDE** : To a wide angle.
- **TELE** : To turn to a telescopic range.
- **FAR** : To make focus far manually.
- **NEAR** : To make focus near manually.
- **OPEN** : To open iris.
- **CLOSE** : To close iris.
- **ON** : Switch on the setting of function.
- **OFF** : Switch off the setting of function.
- **F1** : Auxiliary control buttons.
- **F3**: Switching control between intelligent speed dome and multiplexer.
- [0]-[9] : Number key
- [Clear] : To clear inputted data
- [Enter] : To confirm
- 2. Rear Panel (Figure 2)



(Figure 2)

- A. Power input connector: input DC12V power.
- B. ID-Code switch: Used to set the protocol in use and the baud rate of communications.
- C. Communication connector RS485: The controller is connected to adapter box by specific cable.

IV. Setting of the Keyboard

a) The protocol in use and the baud rate of communication of the keyboard are set by the ID-CODE in Figure 2. DIP1-DIP4 are used to select type of the communication protocol as per following table:

| TVDE | | PRO | BAUD RATE | | | |
|--------------|-------|-------|-----------|-------|-------|-------|
| IIFE | DIP-1 | DIP-2 | DIP-3 | DIP-4 | DIP-5 | DIP-6 |
| A01 | OFF | OFF | OFF | OFF | ON | OFF |
| SAMSUNG | ON | OFF | OFF | OFF | OFF | ON |
| B01 | ON | OFF | OFF | OFF | OFF | ON |
| NEON | ON | OFF | OFF | OFF | OFF | ON |
| Santachi | OFF | ON | OFF | OFF | OFF | ON |
| PELCO-D | ON | ON | OFF | OFF | OFF | OFF |
| PELCO-P/4800 | OFF | OFF | ON | OFF | ON | OFF |
| PELCO-P/9600 | | | | | OFF | ON |
| PANASONIC | ON | OFF | ON | OFF | OFF | ON |
| HUNDA600 | ON | ON | ON | OFF | OFF | ON |
| LILIN | OFF | OFF | OFF | ON | OFF | ON |
| VICON | ON | OFF | OFF | ON | ON | OFF |
| KALATEL | ON | ON | OFF | ON | ON | OFF |
| VCL | OFF | OFF | ON | ON | OFF | ON |
| ALEC | OFF | ON | ON | ON | OFF | ON |
| Ultrak | ON | ON | ON | ON | OFF | ON |

b) DIP5 and DIP6 are used to select the baud rate, shown as following table (DIP7 and DIP8

are not used) :

| Baud | Status of ID-CODE | | | | | | | |
|----------|-------------------|------|------|------|------|------|------|------|
| Rate | DIP1 | DIP2 | DIP3 | DIP4 | DIP5 | DIP6 | DIP7 | DIP8 |
| 2400bps | | | | | OFF | OFF | | |
| 4800bps | | | | | ON | OFF | | |
| 9600bps | | | | | OFF | ON | | |
| 19200bps | | | | | ON | ON | | |

c) Some of the ID-CODE of the protocols are set as follows:



d) Switching control between speed dome and multiplexer : The controller can be operated in two modes: Speed Dome and Multiplexer. When power supply is on it is operated on the default mode, namely, the Speed Dome. Alternatively you can control it by pressing [F3] down until the LCD displays "CONTROLLING MULX", then control the multiplexer by the RS-232 output of the keyboard. The RS-485 output of the keyboard cannot be used to control the multiplexer. When operation, please pay attention to the information on the LCD.

V. Operation of the Keyboard

1. Select Address of the Speed Dome Camera : [CAM]+[N]+[Enter]

Display: Current CamID: 001

Description : N - No. of camera from 0 to 255

Function : Select the address of the camera to be controlled. When the value N is in conformity with the

address of the Speed Dome Camera, it will be under control.

2. Set the Preset Position : [PRESET]+[N]+[Enter]

Display : Preset No : 001

Description : N — No. of preset position from 1 to 128.

Function : Store current position and refer it as No. N position.

3. Call the Preset Position : [CALL]+[N]+[Enter]

Display : Call Number : 001

Description: : N — No. of preset position from 1 to 128.

Function: Transfer the camera to the position of No. N preset position.

4. Cancel the Preset Position:[**PRESET**]+[**N**]+[**OFF**]

Display: Preset No: 001

Description : N — No. of preset position from 1 to 128.

Function : Delete the No. N preset position stored.

- 5. Set the Cruise Track (NEON, SAMSUNG, PELCO-D, PELCO-P Available) :
 - Enter the Status of Track Setting : [SHOT]+[N]+ [ON] (N : No. of track from 1 to 6).

Display : Track = 01 Sum = 06

Description : Track No.1 is currently setting, in which there are 6 preset points.

• Edit Track : Press **[TELE]** to edit down page and press **[WIDE]** to edit up page. Each track involves 16 preset points and the running speed and the dwelling time of each preset position.

| Display : | No. : 01 | Point: 001 | \rightarrow | Description : The 1st preset position in the track is 001. |
|-----------|----------|-------------|---------------|---|
| Display : | No. : 01 | Speed : 001 | \rightarrow | Description : The speed of the 1st preset point in the track is |
| | | | | the 1st class. |
| Display : | No. :01 | Time : 004 | \rightarrow | Description : The dwelling time of the 1st preset point in the |

track is 4 seconds

• Speed Range : 1 to 8 from the fastest to the lowest. Any speed outside the range will be referred as

the 1st class; the range of the dwelling time is : 1 to 255.

- When the No. N preset point is set as No. 0, then all preset points before the No. N preset point in the track will be valid however all numbers of preset points afterward and their speed and dwelling time shall be set as 0 automatically.
- After tracks are edited, press OFF to store and exit while push the joystick to exit without storage.
- 6. Run Cruise Track: [SHOT]+[N]+ [Enter]

Display: Input Tour No: 01

Description : N — No. of the track from 1 to 6.

Function : Tour the No. N track and stop tour by pushing the joystick.

7. Stop Cruise Track: [SHOT]+[N]+ [OFF]

Display : Input Tour No : 01

Description : N — No. of the track from 1 to 6.

Function : Stop the No. N track or stop tour by pushing the joystick.

8. Cancel Cruise Track: [SHOT]+[N]+ [OFF] (Pressing [OFF] down until "Clear Tour OK "appears)

Display: Input Tour No: 01

Description : N — No. of the track from 1 to 6.

Function : Delete the No. N track

9. Auto Pan ON (Operation of NEON, SAMSUNG Protocol): [AUTO]+[P1]+[ON]+[P2]+[OFF]
 Display : Input 1st No : 001

Description : P1----- the starting scan No. of preset point from 1 to 128, which should be set already.

Display : Input 2nd No : 002

Description : P2—— the ending scan No. of preset point from 1 to 128, which should be set already.

If P1 = P2 or P1 and P2 are coincided, the speed dome will make scan in range of 360° .

Note:

(1) For PELCO-D and PELCO-P Protocols the way of operation is as follows:

- Set the Starting Scan Position: Transfer the speed dome to the starting scan position, operation [AUTO]+[ON]
- Set the Ending Scan Position: Transfer the speed dome to the ending scan position, operation [AUTO]+[OFF]
- Run Auto Pan : [AUTO]+[ENTER]

(2) Auto Pan operation takes the following parameters. You must set these parameters before using a Auto Pan command to begin the scan operation. You can use the scan Stop command or PT scan stop command to stop the scan. Setting scan condition:

- Auto Pan Position(First specify position, second specify position)
- Auto Pan Speed and Direction.
- 10. Stop Auto Pan :[AUTO]+[OFF] (only for NEON , SAMSUNG protocol) or push the joystick to stop scan.
- 11. Control the Zoom of the Camera : [WIDE]/[TELE]
- 12. Control the Focus of the Camera : [FAR]/[NEAR]
- 13. Control the Iris of the Camera : [OPEN]/[CLOSE]
- 14. Auxiliary Control of the Camera : By combination of [F1] and [ON], [OFF] buttons, you can set some

data of the camera, and functions are listed as follows :

| No. of | Control Object | Definition of Keyboard Operation | | | |
|---------|--|----------------------------------|------------------------------|--|--|
| Value N | Collubri Object | [F1]+N+[ON] | [F1]+N+[OFF] | | |
| 0 | Camera Power Supply/Reset Control | Power ON/OFF Switching | Camera Reset | | |
| 1 | Back Light Compensation | ON | OFF | | |
| 2 | Zero Illumination | ON | OFF | | |
| 3 | Display | ON | OFF | | |
| 4 | Digital Zoom | ON | OFF | | |
| 5 | Back Light of Keyboard Screen | ON | OFF | | |
| 6 | Focus | Automatic | Manual | | |
| 7 | Iris | Automatic | Manual | | |
| 8 | | Automatic | Manual | | |
| 9 | White Balance Mode (WB) | Indoor Mode | Outdoor Mode | | |
| 10 | | ATW Mode | One Push WB | | |
| 11 | Black & White/Color Switching | Color | Black & White | | |
| 12 | Set Auto Pan (Only conditions for scan. If | $< 180^{\circ}$, low speed | $> 180^{\circ}$, low speed | | |
| 13 | start scan, operate as Item 9 in this | < 180°, middle speed | > 180°, middle speed | | |
| 14 | paragraph) | < 180°, high speed | $> 180^{\circ}$, high speed | | |

- 15. Use the Joystick to control the speed dome camera : You can use the speed joystick to control the Pan/Tilt direction and speed of the speed dome randomly. The speed of pan/tilt is decided by the angle of the joystick you operated (Figure 3). Change the tilting angle of the joystick you can adjust the speed evenly and the camera can be focused automatically in the course of scan to keep images being distinct.
- 16. In case error operation occurs, normal display will be recovered after "Error Operation" appears for 1 second.



VI. Installation and Connection:

and the multiplexer (Figure 8)

Attention : Please read the operation manual of the keyboard and the speed dome carefully before connecting

wires. Any incorrect connections can cause permanent damage of the device. When connecting wires, first switch

off the power supply of all devices. The communication wires between devices should be shielded twisted cable. When installing cables they should be far away from high voltage lines or other possible interference circuits as can as possible.

- 1. The marking of wires of the transfer box (Figure 4)
- 2. Connections of the keyboard controller controlling multiple speed dome cameras (Figure 5)
- 3. Connection Drawing between the keyboard and the multiplexer via the address box (Figure 7)
- 4. System Connection Drawing between the keyboard and the dome camera











- VII. Technical Specifications :
 - Communication between Speed Dome Camera and Controller : Port to multi-port and half duplex function.
 - Communication connector: RS-485.
 - Baud Rate of Communication : Four baud rates i.e. 2400bps, 4800bps, 9600bps and 19200bps.
 - Distance of Communication : 1200m in maximum
 - Power Supply : DC12V/1A
 - Size : 315 × 165 × 57 (mm)
 - ♦ Weight : 2 Kg
 - Number of controlled speed dome camera up to 32.
- VIII. Points for Attention :
 - Please read the operation manual of the keyboard carefully before using it.

- The operation manual is mainly focused on all functions of **PELCO-D**, **PELCO-P** and **NEON** Protocols. For other different protocols, operations could be something different and those different parts will be listed on "**Supplementary Description of the Keyboard Controller**" in details.
- The keyboard takes DC12V power supply. Please confirm the voltage and polarity before the power supply is switched on.
- Do not place the keyboard under the rain or on wet place so as to avoid short circuit or electrical shock.
- As the keyboard is a sophisticated electronic device, you should never open the case so as to avoid the occurrence of trouble.
- The keyboard has integrated multiple protocols, and you are pleased to select correct protocol and the baud rate. When switching on power supply, take care of the selected protocol and the baud rate on the first screen.
- In case the keyboard controls the multiplexer, the operation of combination buttons is as follows: Press one button first, and press the other button after release the first one.

For example : When enter/exit setting of the menu (Function + Zoom), press Function button first, and

press **Zoom** button after **Function** button is released. While use **Func** alone, please put it down until "Motion Detect OK" appears.

- When control the multiplexer through adapter box, select the multiplexer address:
 N + CAM/ID (N: multiplexer address 1--128).
- ♦ In case the keyboard controls the multiplexer, select the camera (1-16): N + Enter N: channel Number (1--16).
- When the keyboard controls the multiplexer, please refer to concerned operation manual of the multiplexer.